

# Milestone Three

FLORIDA TECH IGVC

# Milestone 3 Matrix

#	Task	Percentage	Will	Adam	Chris	Brent	To Do
1	Finished GUI	30	15	15	0	70	none
2	Optimized Navigation Algorithm	70	0	30	0	70	Improve time
3	RabbitMQ Clients for each software component	80	100	0	0	0	Motor control
4	Finished Line Following	90	0	0	100	0	Shading
5	LIDAR Integration	**	25	0	75	0	none
6	IOP Test Client	20	0	100	0	0	Understand documents
7	IOP Nav Platform	20	0	100	0	0	Understand documents
8	Control Component	20	50	50	0	0	Fill in states
9	Integration Testing MQ Clients and IOP	50	50	50	0	0	In progress
10	Integration Testing Components	50	25	25	25	25	Finish components

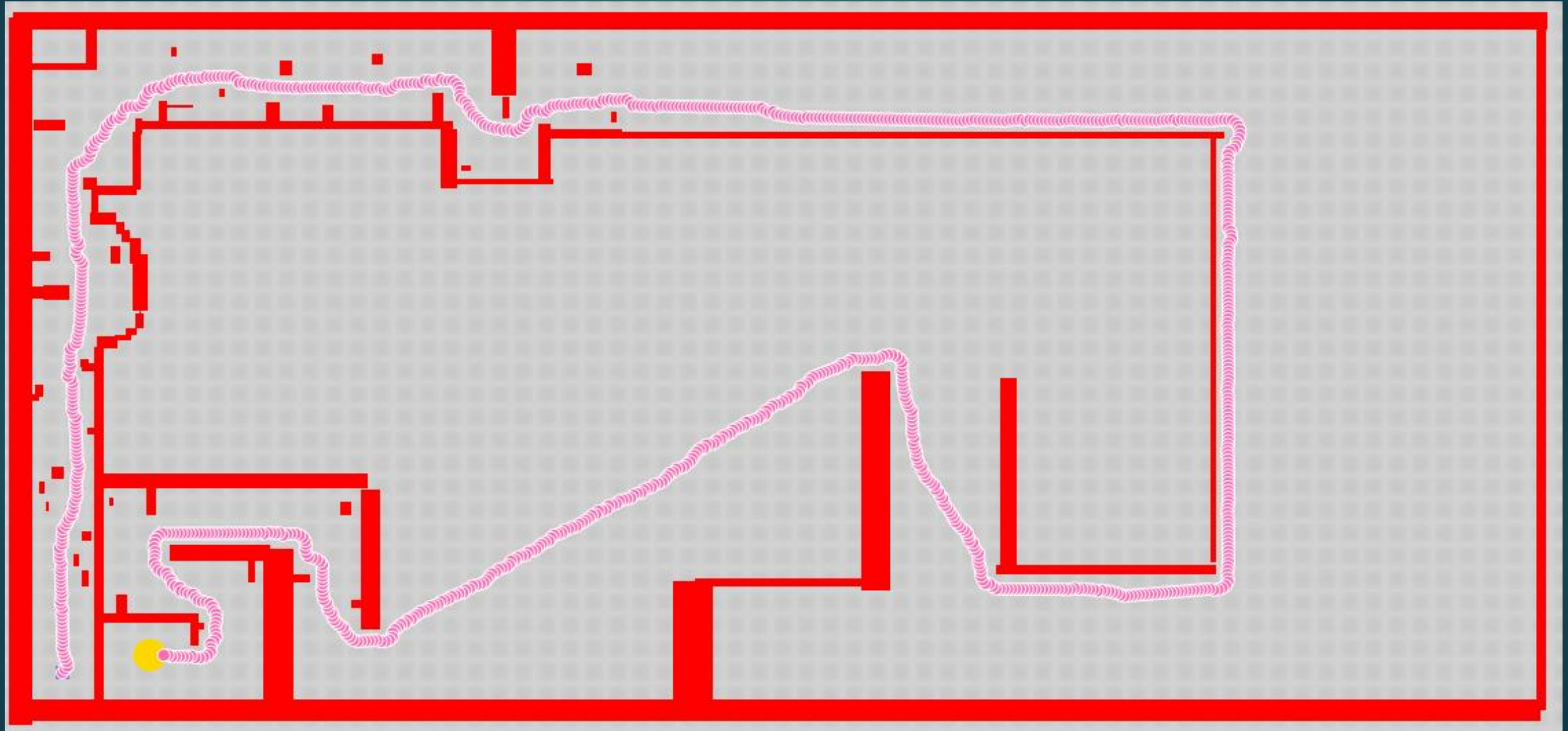
# Navigation

- ▶ Focus on understanding:
  - ▶ Impact of parameters on time / space complexity
    - ▶ Branching Factor
    - ▶ Vehicle Size
    - ▶ Time Step
  - ▶ Space complexity of map usage

# Navigation

- ▶ Findings:
  - ▶ Parameter: Branch factor
    - ▶ Affects runtime linearly
  - ▶ Parameter: Vehicle size
    - ▶ Affects map representation size quadratically
  - ▶ Parameter: Time Step
    - ▶ Doesn't really matter, except that optimal values increase accuracy
  - ▶ Anticipated (complete) map representation size: ~5 megabytes
    - ▶ Not worth spending time optimizing
  - ▶ Increased map resolution bogs down runtime
    - ▶ Halving a map's resolution cut runtime from ~9.5 to ~1.5 seconds!

# Navigation: 1200x600 (and 600x300)



# Navigation: Future Work

- ▶ Understand, integrate LPA\* algorithm to shorten re-compute time
- ▶ Determine optimal parameters to keep runtime low

# Vision

- ▶ Edge detection in various lighting conditions at various angles
- ▶ Issues
  - ▶ Shading
- ▶ TODO
  - ▶ Background deletion
  - ▶ Luminescence calculations
  - ▶ Polarizing lenses

# Communication

- ▶ C++ multi-threaded communication client for GPS
- ▶ All individual Java RabbitMQ communication clients created
- ▶ Helped FSU design their software components
- ▶ Issues
  - ▶ There is a bug in the C++ AMQP library regarding publishing and receiving messages in the same thread



# IOP

- ▶ Purchased three documents
- ▶ Have RelaxNG XML Schema for all 8 core services
  - ▶ Need to translate into usable Java code
  - ▶ Attempted using RelaxNGCC, however getting errors for unknown reasons
- ▶ Looking at using JAUS Toolset as an alternative
  - ▶ <http://jaustoolset.org/>

# Milestone 4 Matrix

#	Task	Will	Adam	Chris	Brent
1	Finish Navigation	15	15	0	70
2	Standardize Message Formats	25	25	25	25
3	Vision & Motor Control RabbitMQ Clients	100	0	0	0
4	Line recognition and Obstacle recognition	0	0	100	0
5	Help FSU develop software	40	10	40	10
6	IOP Test Client	0	100	0	0
7	IOP Nav Platform	0	100	0	0
8	Control Component	33	33	0	33
9	Integrating Components and Integration Testing Components	25	25	25	25